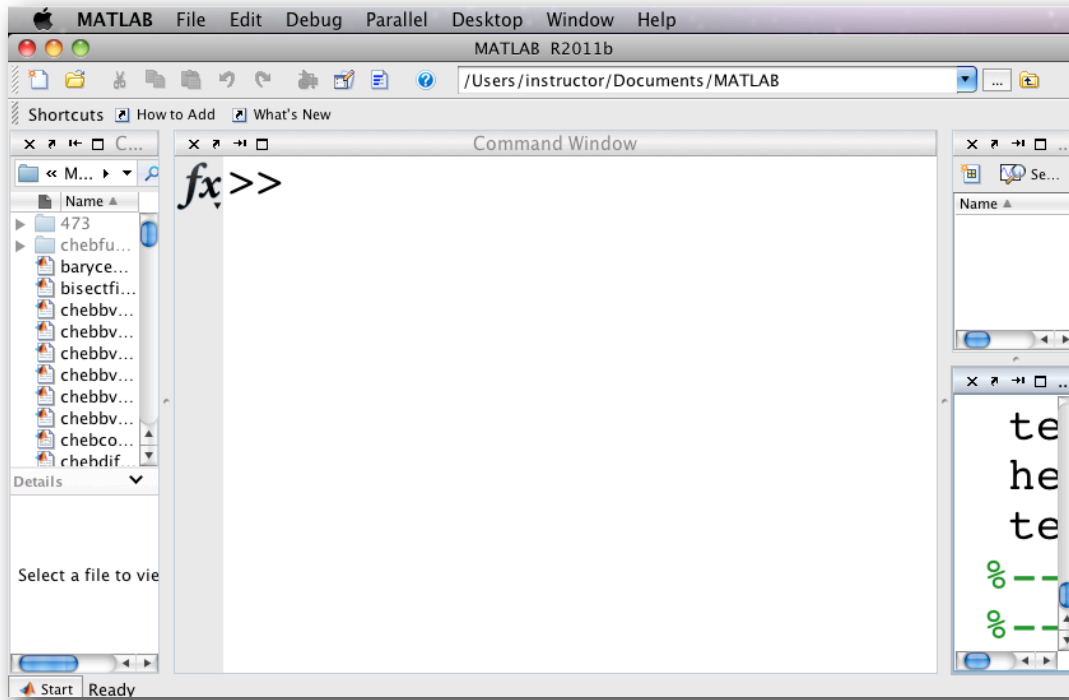


The following figure shows MATLAB when it first starts up.



Here is an edited log of a demo showing how to use the basic features MATLAB (or Octave)

**Enter an arithmetic expression:**

```
>> 2*(4+3)^2
```

**To see the result DON'T end statements with ';':**

```
>> 2*(4+3)^2;    % No result will be displayed!
```

**Use the “Up Arrow Key” to redisplay the last line entered:**

```
>> 2*(4+3)^2;
```

**Use “format long” to display 15 digits:**

```
>> format long
```

```
>> pi
```

**Use “format short” to display 4 digits:**

```
>> format short
```

```
>> pi
```

**Use “format short e” to display 4 digit scientific notation:**

```
>> format short e
```

```
>> pi
```

```
>> 123456789
```

**Use “format long e” to display 15 digit scientific notation:**

```
>> format long e
>> 1234567890/11
```

**Use “format short g” to display using the least space:**

```
>> format short g
>> 1234567890/11 % Note the division operator '/'
```

**Use “format long g” to display using the least space:**

```
>> format long g
>> 1234567890/11 % Note the division operator '/'
```

**Standard functions:** sqrt(x), exp(x), abs(x), log(x), log10(x), factorial(x).

**Trig functions:** sin(x), cos(x), tan(x), cot(x).

**Other functions:** round(x), fix(x), ceil(x), floor(x), rem(x,y), mod(x,y), sign(x).

**For n! use:**

```
>> factorial(100)
```

**The “floor” function:**

```
>> floor(5/2)
>> floor(-5/2)
```

**The “mod” function:**

```
>> mod( 27, 4)
>> mod(-27, 4)
```

**Scaler variables:**

```
>> x = 25
>> x = 3*x - 10
>> a = 15
>> B = 10
>> C = (a + B)*(a - B)+1
```

**How are the next two different?**

```
>> a = 1, B = 2;
>> a = 1; B = 2;
```

**Remember trig function arguments are in radians!**

```
>> theta = 0.85;
>> E = sin(theta)^2 + cos(theta)^2
```

**Predefined variables:** ans(= previous), pi, eps(= smallest delta), inf, i(or j), NaN.

```
>> pi
>> eps
>> inf
>> NaN
>> i
```

**Useful commands:** who, whos, clear, clear x, y, z

**To see the currently defined objects, enter**

```
>> who
```

**or**

```
>>whos
```

**To remove the global variables 'a' and 'B', enter**

```
>> clear a, B
```

```
>> who
```

**To remove all previously defined global variables, enter**

```
>> clear
```

```
>> who
```

**For help, enter**

```
>> help
```

## **Part 2: Creating vectors and arrays**

**Both MATLAB and Octave and are designed to be array calculators!**

**Moreover, they are designed to work with data**

**Representation of population data:**

```
>> format short;
```

**Use “,” or space to create a row vector:**

```
>> yrs = [1984, 1986, 1988, 1990, 1992, 1994, 1996]
```

**Here is a better way to create the yrs vector!**

```
>> yrs = [1984: 2: 1996]
```

**Use “;” to create a column vector.**

```
>> pop = [127; 130; 136; 145; 158; 178; 211]
```

**Use spaces to create a row vector:**

```
>> pt = [1 2 3] %A row vector
```

**Also, You can use RETURN to create a column vector:**

```
>> ptV = [1 % Press Return after entering each coordinate.
```

```
2
```

```
3
```

```
] % Type "]" to end the vector
```

**The general form to create a row vector is vName = [startValue: increment: endValue]**

**BUT increment defaults to 1 if omitted.**

```
>> x = [-5: 5]
```

**However, the square brackets can be omitted for vectors!**

```
>> x = -5: 5
```

**The increment can be negative; hence, it can be used to decrement!**

```
>> x = [10: -1 :0]
```

**The vector yrs can also generate by using the number of values:**

```
>> yrs = linspace(1984, 1996, 7) %Note the commas!
>> x = linspace(-1,1, 10)
```

**Use v(index) to access a vector's coordinates:**

```
>> x(1)
```

**Note that the indexing of vectors starts at 1 NOT zero!**

```
>> x(0) % Will cause an error!
>> x(3)
>> x(11) % Will cause an error!
```

**Creating arrays (matrices).**

**Use ';' to start a new row. Each must have the same length!**

```
>> a = [1 2; 3 4]
>> a = [1 2 3; 4 5 6; 7 8 9]
>> a = [1 2; 3 4; 5 6]
>> a = [1 2 3; 4 5 6]
>> a = 1; b= 10; c = 100;
>> mat = [a b c; a + b + c, a - b - c, a*b*c ]
>> mat = [linspace(1, 5, 4); linspace(10, 15, 4)]
```

**Predefined array constructors: zeros, ones, eye (a bad pun)**

```
>> zeros(2,3)
>> u = ones(4,4)
>> Identity3by3 = eye(3,3)
```

**Use a single quote ' to transpose an array (matrix)**

```
>> aa = [1 2 3]
>> bb = aa'
>> aa = [1 2; 3 4; 5 6]
>> bb = aa'
```

**Accessing vector and array entries:**

```
>> v = [1 2 3]
>> v(1)
>> v(2)
>> v(4) % Another invalid index
>> v(1) = 10

>> v(1)*v(3) + v(2)
>> mat
>> mat(1,1)
>> mat(1,2)
>> mat(1,5)
>> mat(1,1) + mat(2,2)
```

```

>> v = linspace(1,100,100); % <= Note ' ; ' is used to suppress output!
>> v(2:6) % => The entries v(2) to v(6)
>> a = [1 2 3; 4 5 6; 7 8 9]
>> a(:, 1)      % First column
>> a(1, :)     % First row
>> a(:, 1: 2)  % columns 1 and 2
>> a(1: 2, :)  % rows 1 and 2
>> a(2: 3, :)  % rows 2 and 3
>> a(2: 3, 1: 2) % submatrix of a
>> v = 1: 2: 5
>> v = [1: 2: 5] % same result!
>> v = 1: 100;
>> u = v([3, 5, 7: 10]) % entry selection via a vector
>> a = [10: -1: 4; ones(1, 7); zeros(1, 7)] % mat construction

```

### Changing vector and arrays:

```

>> v = [1 2 3 4]
>> v(5: 10) = 10: 5: 35 % Appends entries to a vector
>> mat = [1 2 3 4; 5 6 7 8]
>> mat(3, :) = [10: 4: 22] % Appends a third row
>> mat(1, :) = [] % Removes the first row
>> v = 1: 100;
>> v(2: 99) = [] % Removes entries 2 through 99
>> length(v)
>> length(mat)
>> size(mat)
>> diag(v) % Create a diagonal matrix from 'v'
>> diag(mat) % Create a column vector from the diagonal entries of 'mat'
>> mat
>> mat = [1 2 3 4 5 6; 7 8 9 10 11 12; 13 14 15 16 17 18]
>> reshape(mat, 2, 9)
>> reshape(mat, 9, 2)

```

### Standard Operations on matrices

#### 1. The Determinant

```

>> mat = diag([1 2 3])
>> det(mat)

```

#### 2. Sum and Difference

```

>> v = [1 2 3]; w = [4 5 6];
>> v + w
>> v - w

```

#### 3. Matrix Multiplication

```

>> v*(w') % = v * transpose(w)
>> v'*w % = transpose(v) * w
>> a = [1 2; 3 4; 5 6]
>> a*[1 1]' % = a* transpose([1 1])
>> v

```

```
>> v*a % = (1 X 3)*(3 X 2) = 1 X 2
>> a*v % = (3 X 2)*(1 X 3) ==> ERROR
```

#### 4. The Inverse of a Square Matrix

```
>> a = [1 2; 3 4]
>> inv(a); % = inverse of a square matrix
>> ans
>> a*ans % = 2 X 2 identity
>> a = [1 2 3; 0 4 5; 0 0 6]
>> inv(a)
>> a*inv(a)
>> inv(a)*a
>> a*inv(a) - inv(a)*a % Note: This should be all zeros!
```

#### 5. Finding the Solution of a Linear system of Equations

```
\ <=> left division by a matrix,
/ <=> right division by a matrix
```

Here are two methods for finding the solution of

$$\begin{aligned} 4x - 2y + 6z &= 8 \\ 2x + 8y + 2z &= 4 \\ 6x + 10y + 3z &= 0 \end{aligned}$$

**Method 1: Use  $AX = B \Rightarrow X = A^{-1}B$  (left division by A)**

**Method 2: Use  $X^t A^t = B^t \Rightarrow X^t = B^t(A^t)^{-1}$  (right division by  $A^t$ )**

```
>> A=[4 -2 6; 2 8 2; 6 10 3]
>> B = [8 4 0]'
```

```
>> X = A\B % left division by A is the same as
>> X = inv(A)*B
```

```
>> X = B'/A' % right division by A' is the same as
>> X = B'*inv(A')
```

**Random matrices can be generated!**

```
>> b = rand(3, 3)
```

**Elementwise operators “.\*”, “./”, “.^” NOTE THE PERIODS!**

```
>> a = [1 2 3]
>> b = [2 4 8]
```

#### 1. Elementwise multiplication

```
>> a.*b
```

#### 2. Elementwise division

```
>> a./b
>> a.\b
```

**3. Elementwise power**

```
> > a.^b
```

**Vector-matrix functions:** mean, max, min, median , sum, std, sort.

```
>> a = [1 2 3; 0 4 5; 0 0 6], mean(mat)
```

```
>> max(a), min(a), sum(a)
```

```
>> median(a)
```

```
>> a = linspace(1, 100, 100);
```

```
>> sum(a)
```

```
>> median(a)
```

```
>> max(a)
```

```
>> std(a)
```

```
>> a = [9: -1: 1]
```

```
>> sort(a)
```

**The dot and cross product functions:**

```
>> dot([1 2 3], [3 2 1])
```

```
>> cross([1 0 0], [0 1 0])
```

**Part 3: Plotting****A. 2D Plotting****1. Simple 2D plotting**

```
>> x = [-2: 1: 2] % The x-values
```

```
>> y = x.*x % The y-values = the squares of the x-values
```

```
>> plot(x, y)
```

```
>> x = [-2: 0.1: 2]; % Need more points for a good plot!
```

```
>> y = x.*x;
```

```
>> plot(x, y)
```

**2. Setting Plot Attributes:**

```
>> plot(x, y, 'r') % Curve is red
```

```
>> plot(x, y, 'g', 'LineWidth', 2) % Curve is green and thicker
```

```
>> plot(x, y, 'g:d', 'LineWidth', 2)
```

```
>> plot(x, y, 'b:d', 'LineWidth', 2, 'markersize', 4)
```

```
>> plot(x, y, 'y:d', 'LineWidth', 2, 'markersize', 2)
```

**3. Plotting Several Functions With Labels, Axes, and Grid****A. Setting the plot color and line width**

```
>> x = [-2*pi: 0.1: 2*pi];
```

```
>> y = x.*cos(x); % note use ".*" to generate y's.
```

```
>> plot(x, y, 'r', 'lineWidth', 2)
```

**B. Plotting Several Functions with Labels**

```
>> hold on % keep the current plot
```

```
>> plot(x, sin(x), 'g', 'lineWidth', 10) % Overlay a plot of the sine
```

```
>> hold off
```

**C. Setting an the box axes**

```
>> axis([-6 6 -6 6], 'square') % Set the axes
```

**D. Adding an x,y-axes**

```
>> hold on % keep the current plots
>> plot( [-6 6], [0 0], 'k', 'lineWidth', 3) % draw x-axis
>> plot( [0 0], [-6 6], 'k', 'lineWidth', 3) % draw y-axis
>> grid on % display a grid
```

**E. Adding labels**

```
>> xlabel('X')
>> ylabel('Y = X COS(X), Y = SIN(X)')
```

**4. 3D Plotting****A. Generate the x and y values**

```
>> x = -2: 0.2: 2; y = x;
```

**B. Generate a 'meshgrid' from the x and y values.**

```
>> [X,Y] = meshgrid(x, y);
```

**C. Evaluate the function  $Z = F(X,Y)$  on the meshgrid**

```
>> Z = 4 - X.^2 - Y.^2; % Note uppercase X, Y and the periods!
```

**D. Plot the surface**

```
>> surf(X,Y,Z)
```

**E. Plot a different surface over the same meshgrid**

```
>> Z = 1./(X.^2 + Y.^2+1); % Note uppercase X, Y and the periods!
>> surf(X,Y,Z)
```

**Part 4: Simple Script Files**

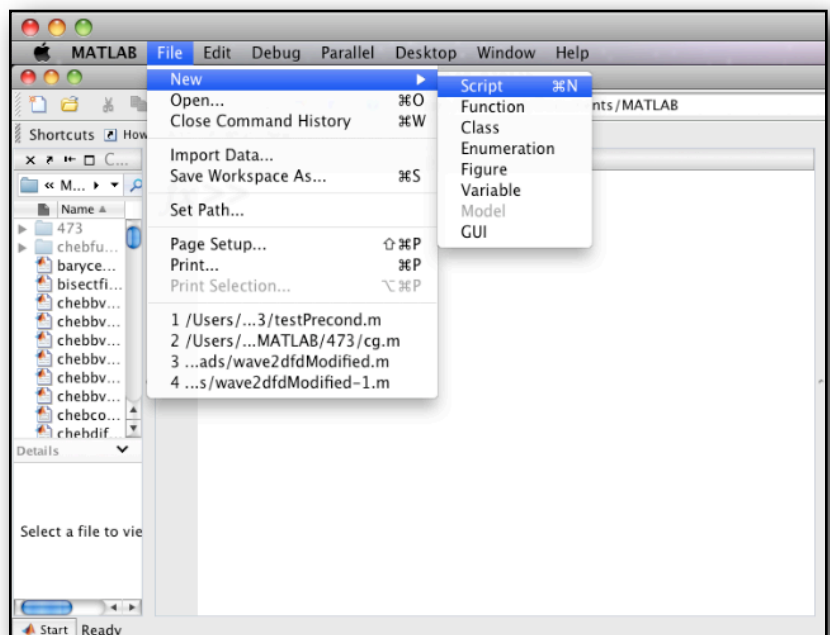
We can create functions and procedures and save them in .m files

**A. Select Functions from the New menu (left top of MATLAB IDE)**

Enter the following in the window that opens and save the function in

a file named "piecewise.m" in a subdirectory yourNameM of Documents directory.

```
function result = piecewise(x)
    if (x < -0.5)
        result = x+1.5;
        return
    elseif (x <= 0.5)
        result = 4.0*x*x;
        return;
    else
        result = 1.0;
        return
    end
end
```





**B. Select Functions from the New menu (left top of MATLAB IDE)**

Enter the following in the window that opens and save the function in a file named “addAxes.m” in the subdirectory yourNameM of Documents directory.

```
function addAxes(xMin,xMax, yMin, yMax, color, thickness)
    hold on;
    plot( [xMin xMax], [0 0], color, 'lineWidth', thickness );
    plot( [0 0], [yMin yMax], color, 'lineWidth', thickness );
    grid on;
    hold off
end
```

For Octave, write them using a text editor and saved them as piecewise.m and addAxes.m in the *Documents* directory.

In both cases, you will need to add a path to this directory to the “search paths”.

```
>> addpath( '~/Documents/yourNameM' )
>> x = -2: 0.05: 2; % Generate the x-values
>> y = arrayfun(@piecewise, x); % Apply piecewise(x) to x-values vector
>> plot(x, y, 'r', 'lineWidth', 3)
>> axis( [-3 3 -1 2] )
>> addAxes(-2, 2, -0.5, 1, 'b', 4)
>> addAxes(-3, 3, -1, 2, 'b', 4)
```

**C. An example function to plot  $Z = F(X,Y)$  over a square  $[a, b] \times [a, b]$  using  $n$  points in each direction. Save the following in the file plot3d.m .**

```
function plot3d(Fhandle, a, b, n)
    x = linspace(a, b, n); y = x;
    [X, Y] = meshgrid(x,y);
    Z = Fhandle(X,Y);
    clf
    surf(X,Y, Z)
end
```

Now call the plot3d function using ‘@(x,y) expression’ for the Fhandle parameter .  
`plot3d( @(x,y) 9 - x.^2 - y.^2 , -3, 3, 50 )`

**D. An example function to plot the contours of  $Z = F(X,Y)$  over a square  $[a, b] \times [a, b]$  using  $n$  points in each direction. Save the following in the file contour2d.m**

```
function contour2d(Fhandle, a, b, n)
    x = linspace(a, b, n); y = x;
    [X, Y] = meshgrid(x,y);
    Z = Fhandle(X,Y);
    clf
    [C, h] = contour(X, Y, Z);
    set(h, 'ShowText', 'on', 'TextStep', get(h, 'LevelStep')*2)
end
```

Now call the `contour2d` function using '@(x,y) expression' for the `Fhandle` parameter.  
`contour2d(@(x,y) 9 - x.^2 - y.^2 , -3, 3i, 50)`

## Part 5: Additional Examples

**A. Create a text file of data points as follows:**

**Step 1: Generate the data**

```
>> s = 0
>> for i = 0:10
    data(i + 1, 1) = i
    data(i + 1, 2) = s
    s = s + i
end
```

**Step 2: Save the data**

```
>> dataFile = fopen('/Users/student/Documents/yourNameData.txt', 'w');
>> fprintf(dataFile, '%6i %6i\n', data);
>> fclose(dataFile);
```

**B. Read and plot data points from a text file:**

**Step 1: Read the data points:**

```
>> dataFile = fopen('/Users/student/Documents/yourNameData.txt');
>> A = fscanf(dataFile, '%d %d', [2 inf]);
>> fclose(dataFile);
```

**Step 2: Extract the x and y values**

```
x = A(1, :)
y = A(2, :)
```

**Step 3: Plot the data**

```
plot(x, y, 'o')
```

**C. Plot a solution to the first-order ODE  $\frac{dx}{dt} = x$  over  $[0, 1]$  with  $x(0) = 1$ .**

```
clf
dxdt = @(t,x) x
ode45(dxdt, [0 1], 1)
```

```
% Check that the solution is x = exp(t)
```

```
hold on
t = 0: 0.1: 1;
plot(t, exp(t), 'r')
hold off
```

**D. Plot a solution to the first-order ODE  $\frac{dx}{dt} = t - x^2$  over  $[0, 5]$  with  $x(0) = 0$ .**

Note this ODE is known to have no solution in terms of elementary functions!  
`dxdt = @(t,x) t-x^2`

**F. Plot a solution to the Foxes and Rabbits first-order Predator-Prey system.**

$$\frac{dR}{dt} = 2R - 1.2RF$$

$$\frac{dF}{dt} = -F + 0.9RF$$

where  $(R_0, F_0) = (1, 0.5)$ .

**Step 1: Create a function that represents the system and save it in RF.m .**

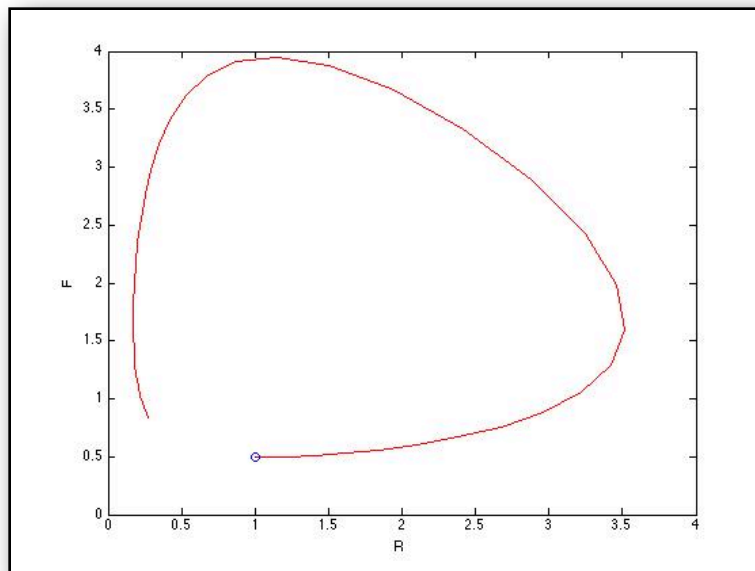
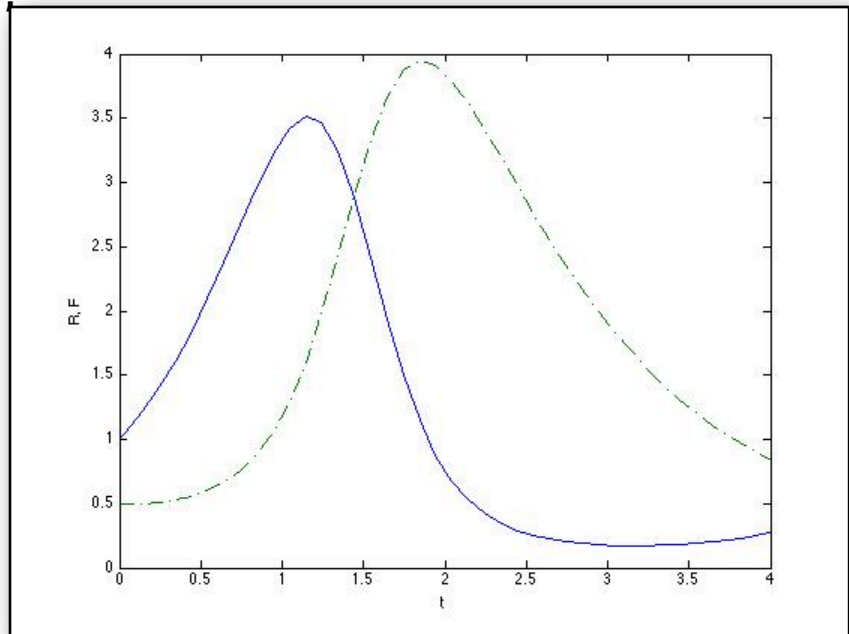
```
function dydt = RF(t,y)
    dydt = zeros(2,1); % a column vector
    dydt(1) = 2*y(1) - 1.2*y(1)*y(2);
    dydt(2) = -y(1) + 0.9*y(1)*y(2);
end
```

**Step 2: Solve the initial-value problem:**

```
[T,Y] = ode45(@RF,[0 4],[1 0.5]);
% Plot R(t) and F(t)
```

**Step 3: Plot the solution:**

```
plot(T,Y(:, 1),'-',T,Y(:, 2),'-.')
% Plot R vs F
figure(2)
plot(Y(:, 1), Y(:, 2))
xlabel('t'); ylabel('R, F')
hold on
plot(1, 0.5, '.')
hold off
```



**G. Generate and play a movie.****A. Generate the first frame of the movie**

```
>> clf % Clear the figure
>> x = -2: 0.2: 2; y = x;
>> [X,Y] = meshgrid(x, y);
>> Z = 4 - X.^2 - Y.^2; % Note uppercase X, Y and the periods!
>> figure('Renderer','zbuffer')
>> surf(X,Y,Z)
>> axis tight
```

**B. Generate the remaining frames of the movie**

```
>> set(gca,'NextPlot','replaceChildren'); % 'gca' = current axes handle
>> for k = 1:20
    % Use  $-1 \leq \sin(2\pi k/20) \leq 1$  to create a periodic function!
    surf(X,Y, sin(2*pi*k/20)*Z)
    F(k) = getframe; % Save the frame in F
end
```

**C. Play the movie**

```
>> movie(F,20) % Play the movie twenty times
```

