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1  ## CSUMS 2-Body Problem CSUMS Spring 2013 A. O. Hausknecht
2  from visual import *
3  from visual.graph import *
4  #Create the scene
5  scene1 = display(title='2-Body Problem',
6                  x=0, y=0, width=700, height=700, center=(0,0,4))
7  ## Data Set
8  b1Mass = 1.5e30
9  b1P0 = vector(      0, 4.5e10, 0)
10 b1V0 = vector( 1.0e10,      0, 0) # Change 1: 1.0e10 to 0 => Looping orbits
11 b1Radius = 0.5e10
12 #
13 b2Mass = 1.5e30 # Change 2: Assuming Change 1 above,
14              # change 1.5e30 to 1.5e20 => Near Circular orbit
15 b2P0 = vector(      0, -4.5e10, 0)
16 b2V0 = vector(-1.0e10,      0, 0)
17 b2Radius = 0.5e10
18 #
19 def initialize():
20     global body1, body2, g1, g2
21     global t, dt, G
22     #
23     t = 0; dt = 0.1 # Time variables
24     G = 6.67e-11 # Universal Constant of Gravitation
25
26     # Create body1
27     body1 = sphere(pos = b1P0 , radius = b1Radius, color=color.yellow,
28                  make_trail=True, trail_type="curve")
29     body1.m = b1Mass
30     body1.v = b1V0
31     body1.a = 0
32
33     # Create body2
34     body2 = sphere(pos = b2P0, radius = b2Radius, color=color.red,
35                  make_trail=True, trail_type="curve")
36     body2.m = b2Mass
37     body2.v = b2V0
38     body2.a = 0
39
40     # Create plots of the bodies speeds
41     gdisplay(x=700, y=0, width=700, height=700,
42            title='speed vs. t', xtitle='t', ytitle='||v||',
43            foreground=color.black, xmin = 0, xmax = 100)
44     g1 = gcurve(color=color.yellow)
45     g2 = gcurve(color=color.red)
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46 #
47 def update():
48     global t
49     t += dt #Increment time
50     dirVector = body2.pos - body1.pos #Direction Vector
51     distSqr = mag2(dirVector) # Distance between bodies Squared
52     norm(dirVector) # Normalize the direction vector
53
54     body1.a = G*body2.m/distSqr*dirVector # Acceleration of body1
55     body1.v += body1.a*dt #Approximate velocity of body1 via Euler's Method
56     body1.pos += body1.v*dt #Approximate position of body1 via Euler's Method
57     g1.plot(pos = (t, mag(body1.v)))
58
59     body2.a = -G*body1.m/distSqr*dirVector # Acceleration of body2
60     body2.v += body2.a*dt #Approximate velocity of body2 via Euler's Method
61     body2.pos += body2.v*dt #Approximate position of body1 via Euler's Method
62     g2.plot(pos = (t, mag(body2.v)))
63 #
64 # Animation loop
65 initialize()
66 while (True):
67     rate(20)
68     update()
69
70
71
72
73
74
75
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